# Application of AIRS v5.0 Averaging Kernels

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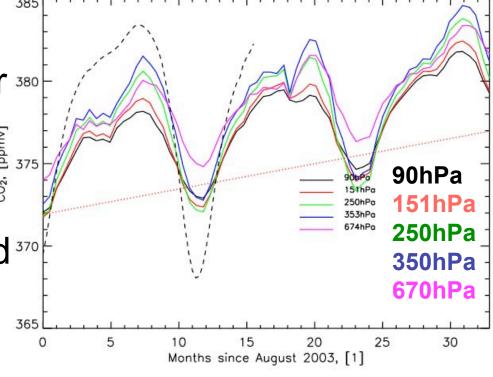
#### **Outline**

- Provide an overview of v5.0 averaging kernels/smoothing operators
  - What are they?
  - How do we apply them and what are the caveats?
- Discuss diagnostic capability of averaging kernels
  - Calculation of retrieval resolution
    - Averaging kernel resolution
    - FWHM error covariance matrices
  - Calculation of statistics using averaging kernels
- Summary and Future Directions

## Biweekly CO<sub>2</sub> from AIRS 3°x3° grids and NOAA ESRL/GMD MBL CO<sub>2</sub>

• Damping of the amplitude seasonal separate is due to our separate vertical sensitivity of the product.

This information
 needs to be conveyed 370
 to modelers and the
 general user
 community.



alat: 60

### What are averaging kernels?

- Averaging kernels are a linear representation of the vertical weighting of retrievals.
  - Related to the amount of information determined from the radiances and how much is due to the first guess [Rodgers, 1976].
    - To some degree avoids aliasing comparisons of in situ measurements vs. retrievals due to incorrect first guesses.
    - Enables assessment of where vertically we have information.
  - Related to the vertical resolution of retrievals [Backus and Gilbert, 1969; Conrath, 1972; Rodgers, 1976; Purser and Huang, 1993]
  - Required by modelers to properly use AIRS trace gas products.
  - Enables assessment of retrieval skill on a case by case basis.
- In the IDEAL case (no damping): A = I : the identity matrix

#### **Averaging Kernels Limitations**

- Our averaging kernels are a conservative estimate of the vertical correlation of products because the startup regression solution (T/H<sub>2</sub>O/O<sub>3</sub>) has it's own averaging kernel.
  - This becomes important only when our products are overdamped.
  - We (NOAA) have the ability to calculate this averaging kernel for case studies if necessary.
- Iteration (esp. background term)/stepwise retrieval complicate interpretation
  - There is a cross-talk between averaging kernels that is not addressed properly.
    - The temperature retrieval believes a fraction of the radiances so that the averaging kernel for products does not exactly relate to the amount of the radiances believed.
    - Separation of signals using propagated noise covariance terms as well as intelligent selection of channels minimizes this effect.
  - Non-linearity (I won't go into this too much here) is not properly handled by the linear averaging kernel analysis.

#### **Averaging Kernels Limitations**

- Vertical weighting is strictly defined on the retrieval grid, not the RTA grid.
  - Any estimate of resolution based on the internal averaging kernels is limited by the resolution of our retrieval functions.
  - Transformations between retrieval functions and AIRS layers exist; however they assume that we can "upsample" derivatives without loss of accuracy.
    - Not a big problem if we have sampled the atmosphere adequately with respect to channel temperature and gaseous kernel functions.

#### A Note on Trapezoidal Functions

• Trapezoidal functions (denoted,  $\mathbf{F}_{L,j}$ ) are used to interpolate retrieval delta's onto the RTA grid:

Fine level/layer  $\Delta x_L = \sum_j F_{L,j} \Delta A_j$  retrieved quantities interpolated onto RTA grid.

These functions serve two purposes:

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- Define a reduced measurement space on which finite difference derivatives are calculated.
- Ensure a smooth product (interpolation).
- Transformation between RTA grid and coarse layers is provided by a least squares estimate:

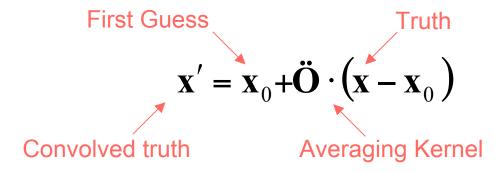
$$\Delta \mathbf{A}_{j} = \sum_{L'} \mathbf{F}_{j,L'}^{+} \Delta \mathbf{x}_{L'} = [\mathbf{F}_{j,L}^{T} \mathbf{F}_{L,j'}]^{-1} \mathbf{F}_{j',L'}^{T} (\mathbf{x}_{L'} - \mathbf{x}_{0,L'})$$

Least squares estimate requires halfbot and halftop forced to .false.

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#### Linear vs. Log derivatives

[Rodgers and Connor 2003] form of the equation assumes linearity in changes in state. For temperature this is true and we have:



For minor constituents (H<sub>2</sub>O, O<sub>3</sub>, CO, CH<sub>4</sub>, etc.) the averaging kernels act in logarithmic or %changes in state:

$$\log(\mathbf{x}') = \log(\mathbf{x}_0) + \ddot{\mathbf{O}} \cdot \log(\mathbf{x}/\mathbf{x}_0)$$

For small perturbations/low information content we can write in terms of % changes relative to the first guess:

Unit vector

$$\mathbf{x}' = \mathbf{x}_0 \left[ \mathbf{1} + \ddot{\mathbf{O}} \cdot \left( \frac{\mathbf{x} - \mathbf{x}_0}{\mathbf{x}_0} \right) \right]$$

#### Retrieval Functions and Convolution Recipe

The retrieval calculates coarse layer derivatives and assigns retrieved changes to fine layers using slb2fin (trapezoids denoted  $\mathbf{F}_{L,i}$ ).

We can handle the trapezoidal retrieval functions in much the same way that the retrieval handles them by:

1. Calculating coarse layer delta states. e.g.,

$$\Delta \mathbf{A}_{j} = \sum_{L'} \mathbf{F}_{j,L'}^{+} \Delta \mathbf{x}_{L'} = [\mathbf{F}_{j,L}^{T} \mathbf{F}_{L,j'}]^{-1} \mathbf{F}_{j',L'}^{T} (\mathbf{x}_{L'} - \mathbf{x}_{0,L'})$$

2. Apply averaging kernel to coarse layer deltas and use the functions to interpolate to the RTA grid.

Minor gases: Let: x = log(x)

$$\Delta \widetilde{\mathbf{x}}_{L} = \widetilde{\mathbf{x}}_{L} - \widetilde{\mathbf{x}}_{0,L} = \sum_{j} \mathbf{F}_{L,j} \cdot \sum_{j'} [\Phi_{j,j'} \cdot \Delta \mathbf{A}_{j'}]$$

3. 'Use convolution equation on interpolated convolved delta state:

$$\mathbf{x'} = \mathbf{x}_0 + \Delta \widetilde{\mathbf{x}}$$

#### Retrieval Smoothing Terms

- Retrieval smoothing is composed two terms:
  - Regularization (e.g. a noise threshold value termed  $B_{max}$ ).
  - Trapezoidal interpolation rule.

#### **Trapezoidal Smoothing**

$$\Delta \hat{\mathbf{x}}_{L} = \mathbf{F}_{L,j} \cdot \ddot{\mathbf{O}}_{j,j'} \cdot [\mathbf{F}_{j',L}^{T} \mathbf{F}_{L,j}]^{-1} \mathbf{F}_{j,L'}^{T} \Delta \mathbf{x}_{L'}$$

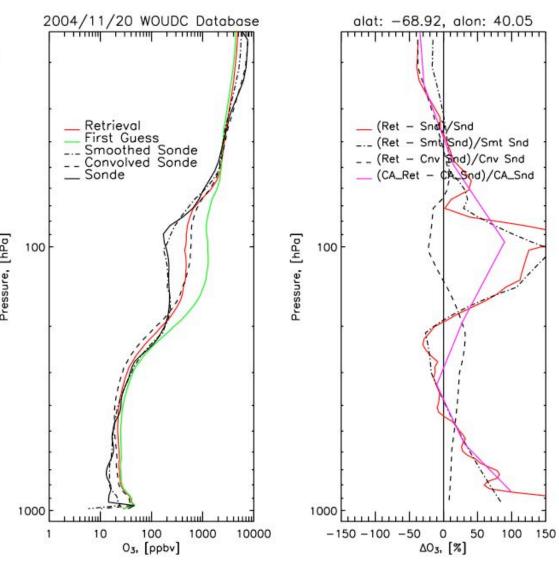
**Averaging Kernel Smoothing** 

- Regression can impart high resolution structure, this structure is removed from the comparison by the trapezoidal smoothing terms if it is finer than the width trapezoids.
- The following slide illustrates each component.

## An example of retrieval smoothing and convolution (O<sub>3</sub> hole S. Pole)

- Smoothed sonde calculated assuming averaging kernelidentity matrix
  - Ideal case -- what we would do in the absence of damping.
- •Convolved sonde using case dependent averaging kernel.

Retrieval and Convolved Sonde Compare very well.



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#### Trapezoidal Null Space

Projecting the truth-fg onto the trapezoids and interpolating onto the RTA grid.

$$\Delta \widetilde{\mathbf{x}}_{L} = \widetilde{\mathbf{x}}_{L} - \widetilde{\mathbf{x}}_{0,L} = \mathbf{F}_{L,j} \cdot \mathbf{F}_{j',L'}^{+} \cdot \Delta \mathbf{x}_{L'}$$

$$\Delta \widetilde{\mathbf{x}}_{L} = \mathbf{F}_{L,j'} \cdot \mathbf{F}_{j',L'}^{+} \cdot \Delta \mathbf{x}_{L'}$$

$$\Delta \widetilde{\mathbf{x}}_{L} = \mathbf{F}_{L,j'} \cdot \mathbf{F}_{j',L'}^{+} \cdot \mathbf{F}_{L',j} \cdot \Delta \mathbf{A}_{j}$$

$$\Delta \widetilde{\mathbf{x}}_{L} = \Delta \mathbf{x}_{L}$$

 $\Delta \widetilde{\mathbf{X}}_L = \mathbf{F}_{L,j'} \cdot \mathbf{F}_{j',L'}^+ \cdot \Delta \mathbf{X}_{L'}$  Components of the unposition  $\mathbf{X}_L = \mathbf{F}_{L,j'} \cdot \mathbf{F}_{j',L'}^+ \cdot \mathbf{F}_{L',j}^+ \cdot \Delta \mathbf{A}_j$  Smoothing error are zero if the difference between the first guess and "truth" can be written as a superposition of the difference between the first guess and "truth" can be written as a superposition of the difference between the first guess and "truth" can be written as a superposition of the difference between the first guess and "truth" can be written as a superposition of the difference between the first guess and "truth" can be written as a superposition of the difference between the first guess and "truth" can be written as a superposition of the difference between the first guess and "truth" can be written as a superposition of the difference between the first guess and "truth" can be written as a superposition of the difference between the first guess and "truth" can be written as a superposition of the difference between the first guess and "truth" can be written as a superposition of the difference between the first guess and "truth" can be written as a superposition of the difference between the first guess and "truth" can be written as a superposition of the difference between the first guess and "truth" can be written as a superposition of the difference between the first guess and "truth" can be written as a superposition of the difference between the first guess and "truth" can be written as a superposition of the difference between the differenc "truth" can be written as a superposition of trapezoidal perturbations!

Standard deviation between smoothed truth and truth (note this is dependent on the trapezoid spacing, variability in the truth and variability in the first guess).

	F <sup>+</sup>	Slab avg.
T(p)	0.25K-0.5K	0.5K-1.0K
H <sub>2</sub> O(p)	5%-10%	10%-20%
O <sub>3</sub> (p)	5%-10%	10%-20%

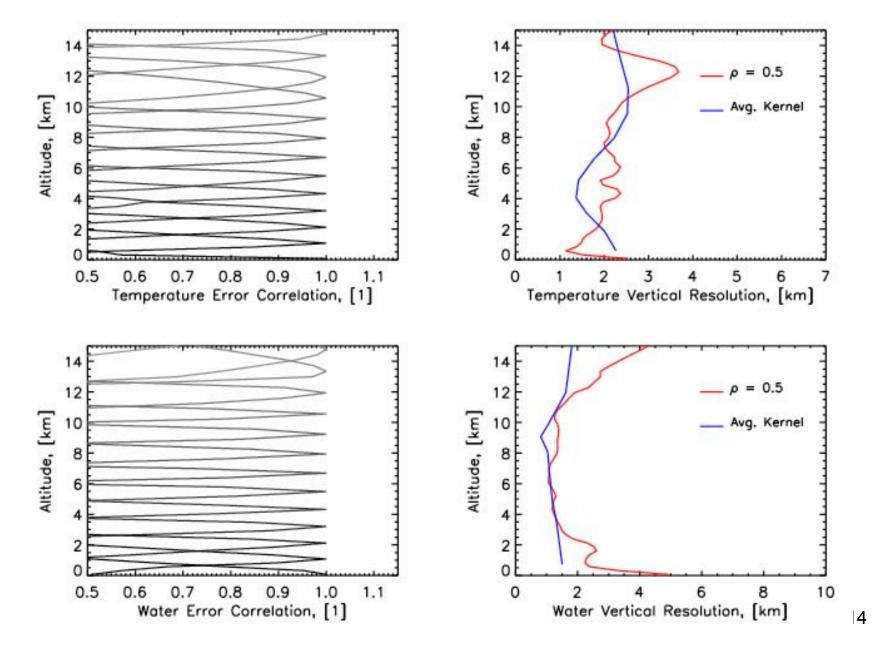
## Resolution estimates from error covariance matrices and averaging kernels

- Vertical resolution of any retrieval is related to the width of the kernel functions and hence averaging kernels.
  - Backus-Gilbert, 1969
  - Conrath, 1972
- We can also define the vertical resolution in terms of the error correlation between atmospheric layers.

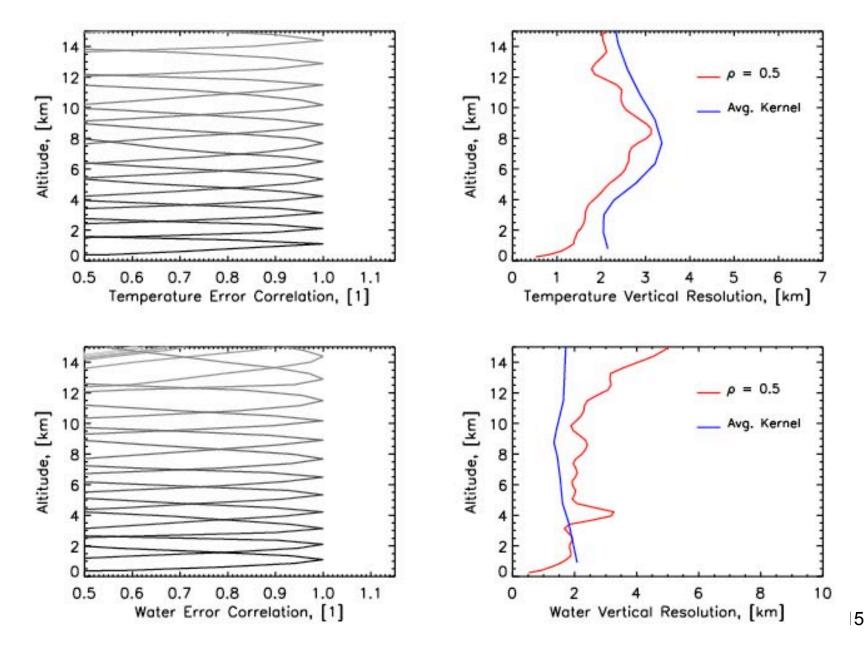
$$\tilde{n}_{i,j} = \frac{\text{cov}(\Delta \mathbf{x}_i, \Delta \mathbf{x}_j)}{\sigma_i \sigma_j}; \quad \Delta \mathbf{x}_i = \hat{\mathbf{x}}_i - \mathbf{x}_i$$
Error correlation matrix

$$\text{Retrieved value at RTA grid index, } i$$

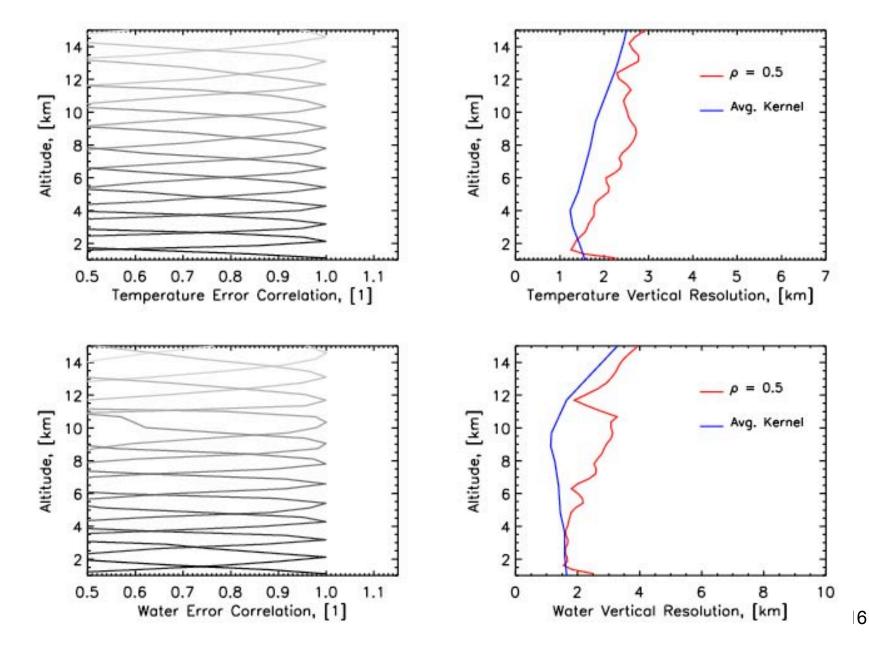
#### Vertical correlation and resolution at ARM-TWP



#### Vertical correlation and resolution at ARM-SGP

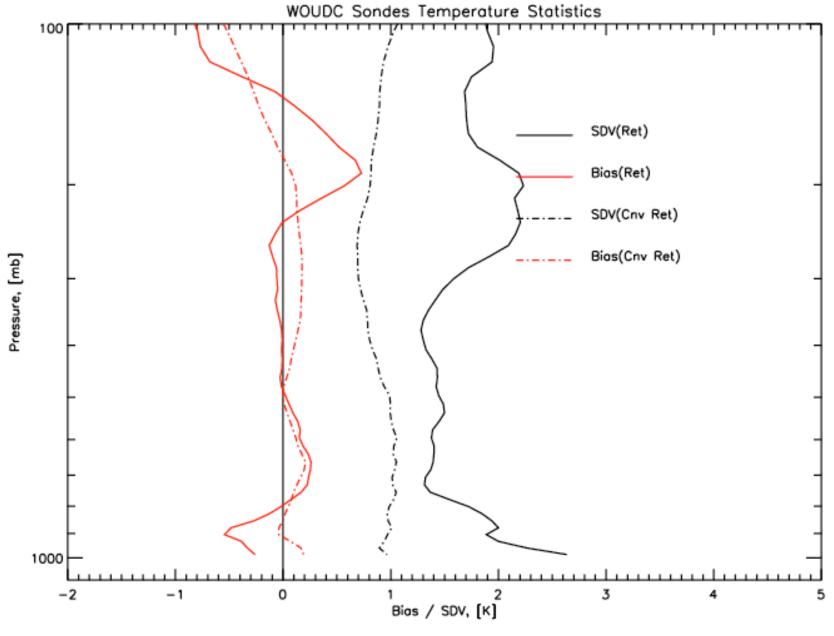


#### Vertical correlation and resolution in NOAA sondes

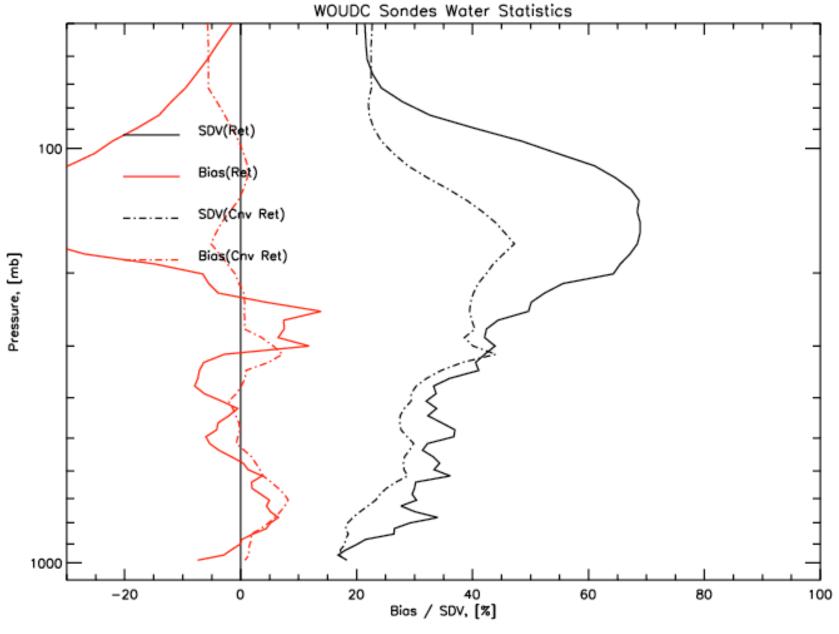


#### Examples of Statistics using Averaging Kernels

- The information content of AIRS spectra is highly scene dependent (e.g. clear vs. cloudy, tropical vs. polar, ocean vs. land, etc.).
   Therefore, the vertical resolution and accuracy of any given retrieval is a function of scene.
- In previous slides we have shown that portions of the retrieval error (e.g. those due to the first guess/trapezoidal smoothing) are beyond the physical retrieval capability.
- It makes sense to use an estimate of the information content on a case-by-case basis for comparisons of retrievals to correlative measurements.
  - Use the averaging kernel/trapezoids to convolve the correlative measurement such the this profile is more comparable to what the retrieval would "see" given that profile.
- WOUDC Ozone/Radiosondes (see M. Divarkarla's talk 9:10 today)
  - Weighted toward polar cases
  - Water from matched operational radiosonde
- Comparisons are for temperature and water only.



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## Summary

- AIRS averaging kernels and smoothing operators enable "fair" comparison of the physical retrieval to correlative measurements
  - smoothing due to trapezoids
  - smoothing due to damping (averaging kernel)
- Accounting for errors due to trapezoidal smoothing gives a lower limit to retrieval ability.
  - MAX 0.5 K for T
  - MAX 10% for H<sub>2</sub>O and O<sub>3</sub>
- Averaging kernel derived resolution is similar in vertical shape to resolution derived from error covariance matrices.
  - averaging kernels for the physical temperature and moisture retrievals are good representations of retrieval vertical weighting

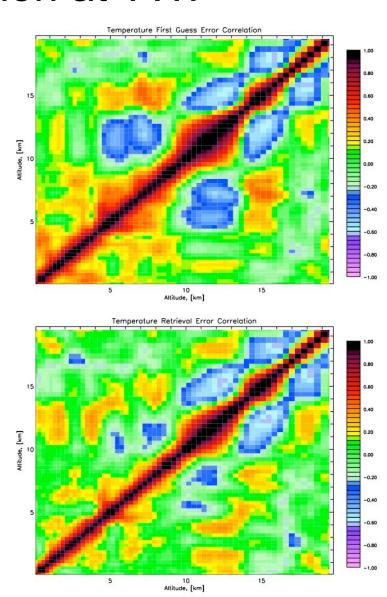
#### **Future Directions**

- Publish results (draft in progress).
- Transformation between 100 layer and trapezoidal functions introduces large scale vertical correlation in 100 layer products
  - Consider using more or different retrieval basis functions (e.g. triangles vs. trapezoids).
- Analysis of information content for ozone in different scenes.

### Questions?

#### **Error Correlation at TWP**

- Physical retrieval error correlation (bottom panel) is more diagonal than the regression error correlation (lower panel)
- Smoothing at the tropopause ~15km is evident in both physical and regression solutions.



### Derivation of averaging kernels

$$\ddot{\mathbf{O}}_{j,j'} = \mathbf{G}_{j,n} \cdot \mathbf{K}_{n,j'}$$

$$\ddot{\mathbf{O}}_{j,j'} = \mathbf{U}_{j,k} \cdot \operatorname{diag}(\frac{\ddot{\mathbf{o}}_{k}}{\ddot{\mathbf{e}}_{k}}) \cdot \mathbf{U}_{k,j'}^{T} \cdot \mathbf{K}_{j',n}^{T} \cdot \mathbf{W}_{n,n'} \cdot \mathbf{K}_{n',j'}$$

$$\ddot{\mathbf{O}}_{j,j'} = \mathbf{U}_{j,k} \cdot \operatorname{diag}(\frac{\ddot{\mathbf{o}}_{k}}{\ddot{\mathbf{e}}_{k}}) \cdot \mathbf{U}_{k,j'}^{T} \cdot \mathbf{U}_{j,k} \cdot \operatorname{diag}(\ddot{\mathbf{e}}_{k}) \cdot \mathbf{U}_{k,j'}^{T}$$

$$\ddot{\mathbf{O}}_{j,j'} = \mathbf{U}_{j,k} \cdot \operatorname{diag}(\ddot{\mathbf{o}}_{k}) \cdot \mathbf{U}_{k,j'}^{T}$$